1. Selecte the General>ALL>16PIN connector>00->EPB



2. Select the Special function



3. Select the Parameter initialization mode



4. Notice

EPB(Electonic parking brake) > Parameter initialization mode	← 🖸
Caution!! Derform parameter initialization while all ECM is connected	<u></u>
- After initialization, must do [Force sensor calibration] function.	
Note :	
This function will perform parameter initialization mode.	
Press [OK] to next.	
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G-Seen Oceani	2
OK CANCEL	

** G-scan will perform the function.

5. Once complete, you will see this message

EPB(Electonic parking brake) > Parameter initialization mode	+	Ō
Note : - Parameter initialization done. - Perform [Force sensor calibration].		~
Press [OK] to finish.		
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G-Scen Ocean	b	~

** After this function is complete, you must now perform the [Force sensor calibration].